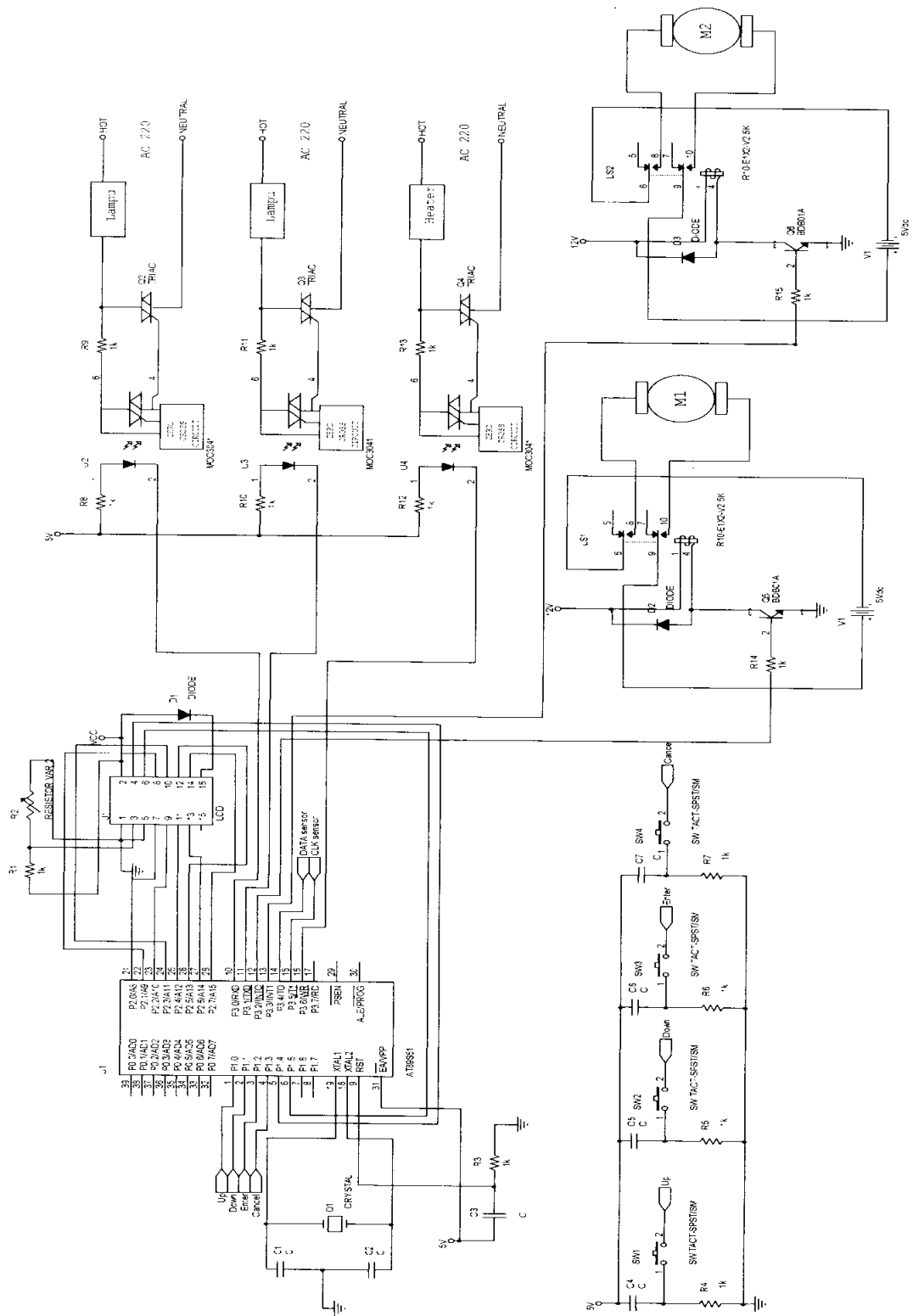


## **LAMPIRAN**

# LAMPIRAN A

## RANGKAIAN KESELURUHAN



## Listing Program

```
#include <at89x51.h>
#include <intrins.h>
#include <math.h>
#include <stdio.h>

typedef union
{ unsigned int i;
  float f;
} value;

enum {TEMP,HUMI};

#define tb_down          P1_0
#define tb_reset        P1_1
#define tb_up           P1_2
#define tb_enter        P1_3
#define finers          P1_4
#define fince           P1_5

#define datalcd          P2

#define lampu_ka        P0_0
#define lampu_ki        P0_1
#define kipas_in        P0_2
#define kipas_out       P0_3
#define pemanas         P0_6

#define DATA           P3_0
```

```
#define SCK                P3_1
```

```
//program sensor dimulai dari sini
```

```
//program sensor dimulai dari sini
```

```
//program sensor dimulai dari sini
```

```
#define    noACK                0
```

```
#define    ACK                1
```

```
#define    STATUS_REG_W    0x06
```

```
#define    STATUS_REG_R    0x07
```

```
#define    MEASURE_TEMP    0x03
```

```
#define    MEASURE_HUMI    0x05
```

```
#define    RESET                0x1e
```

```
char s_write_byte(unsigned char value)
```

```
{
```

```
    unsigned char i,error=0;
```

```
    for (i=0x80;i>0;i/=2)        //shift bit for masking
```

```
        {
```

```
            if (i & value) DATA=1;        //masking value with i , write to SENSI-  
BUS
```

```
        else DATA=0;
```

```
        SCK=1;                //clk for SENSI-BUS
```

```
        _nop_();_nop_();_nop_();        //pulswith approx. 5 us
```

```
        SCK=0;
```

```
        }
```

```
    DATA=1;                //release DATA-line
```

```
    SCK=1;                //clk #9 for ack
```

```
    error=DATA;                //check ack (DATA will be pulled down by SHT11)
```

```
    SCK=0;
```

```
return error;          //error=1 in case of no acknowledge
```

```
}
```

```
char s_read_byte(unsigned char ack)
```

```
{
```

```
unsigned char i,val=0;
```

```
DATA=1;          //release DATA-line
```

```
for (i=0x80;i>0;i/=2)    //shift bit for masking
```

```
{
```

```
    SCK=1;          //clk for SENSI-BUS
```

```
    if (DATA) val=(val | i);    //read bit
```

```
    SCK=0;
```

```
}
```

```
DATA=!ack;          //in case of "ack==1" pull down DATA-Line
```

```
SCK=1;          //clk #9 for ack
```

```
_nop();_nop();_nop();    //pulswith approx. 5 us
```

```
SCK=0;
```

```
DATA=1;          //release DATA-line
```

```
return val;
```

```
}
```

```
void s_transstart(void)
```

```
{
```

```
DATA=1;    SCK=0;          //Initial state
```

```
_nop();    SCK=1;
```

```
_nop();    DATA=0;
```

```
_nop();    SCK=0;
```

```
_nop();_nop();_nop();
```

```
SCK=1;    _nop();
```

```
DATA=1;    _nop();
```

```
SCK=0;
```

```
}
```

```
void s_connectionreset (void)
```

```
{
```

```
unsigned char i;
```

```
DATA=1; SCK=0;           //Initial state
```

```
for(i=0;i<9;i++)        //9 SCK cycles
```

```
{
```

```
    SCK=1;
```

```
    SCK=0;
```

```
}
```

```
s_transstart();         //transmission start
```

```
}
```

```
char s_softreset(void)
```

```
{
```

```
unsigned char error=0;
```

```
s_connectionreset();    //reset communication
```

```
error+=s_write_byte(RESET); //send RESET-command to sensor
```

```
return error;           //error=1 in case of no response form the sensor
```

```
}
```

```
char s_read_statusreg(unsigned char *p_value, unsigned char *p_checksum)
```

```
{
```

```
unsigned char error=0;
```

```
s_transstart();         //transmission start
```

```
error=s_write_byte(STATUS_REG_R); //send command to sensor
```

```
*p_value=s_read_byte(ACK); //read status register (8-bit)
```

```
*p_checksum=s_read_byte(noACK); //read checksum (8-bit)
```

```

return error;          //error=1 in case of no response form the sensor

}

```

```

char s_write_statusreg(unsigned char *p_value)
{
unsigned char error=0;
s_transstart();      //transmission start
error+=s_write_byte(STATUS_REG_W);//send command to sensor
error+=s_write_byte(*p_value); //send value of status register
return error;        //error>=1 in case of no response form the sensor

}

```

```

char s_measure(unsigned char *p_value, unsigned char *p_checksum,unsigned
char mode)
{
unsigned error=0;
unsigned int i;
s_transstart();      //transmission start
switch(mode)
    {
        //send command to sensor
        case TEMP    : error+=s_write_byte(MEASURE_TEMP); break;
        case HUMI   : error+=s_write_byte(MEASURE_HUMI); break;
        default     : break;
    }
for (i=0;i<65535;i++) if(DATA==0) break; //wait until sensor has finished the
measurement
if (DATA) error+=1;      // or timeout (~2 sec.) is reached
*(p_value) =s_read_byte(ACK); //read the first byte (MSB)
*(p_value+1)=s_read_byte(ACK); //read the second byte (LSB)

```

```

*p_checksum = s_read_byte(noACK); //read checksum
return error;
}

```

```

void calc_sth11(float *p_humidity ,float *p_temperature)

```

```

{
const float C1=-4.0;          // for 12 Bit
const float C2=+0.0405;      // for 12 Bit
const float C3=-0.0000028;   // for 12 Bit

float rh=*p_humidity;        // rh:  Humidity [Ticks] 12 Bit
float t=*p_temperature;      // t:   Temperature [Ticks] 14 Bit
float rh_lin;                 // rh_lin: Humidity linear
float t_C;                    // t_C  : Temperature [°C]

```

```

t_C=t*0.01 - 40;             //calc. temperature from ticks to [°C]
rh_lin=C3*rh*rh + C2*rh + C1; //calc. humidity from ticks to [%RH]

```

```

*p_temperature=t_C;          //return temperature [°C]
*p_humidity=rh_lin;         //return humidity linear [%RH]
}

```

```

//program sensor sampai disini
//program sensor sampai disini
//program sensor sampai disini

```

```

void tunda()
{
int a;
for (a=0;a<=500;a++);
}

```



```
void tunda2(int loop2)
{
int loop;
loop=0;
while (loop<=loop2)
    {
    loop++;
    TH1=(-50000/256)-1;
    TL1=(-50000%256);
    TF1=0;
    TR1=1;
    while (!TF1);
    }
}
```

```
void kirim_p(int dat)
{
rs=0;
datalcd=dat;
e=1;
e=0;
tunda();
}
```

```
void initlcd()
{
tunda();
kirim_p(56);kirim_p(56);
kirim_p(56);kirim_p(56);
kirim_p(6);kirim_p(12);
```

```
    kirim_p(1);  
}
```

```
void kirim_k(int dat2)  
{  
    rs=1;  
    datalcd=dat2;  
    e=1;  
    e=0;  
    tunda();  
}
```

```
void clear()  
{  
    rs=0;  
    kirim_p(1);  
}
```

```
void cursorhome()  
{  
    rs=0;  
    kirim_p(2);  
}
```

```
void tampil_suhu_input()  
{  
    kirim_k('M'); kirim_k('A'); kirim_k('S');  
    kirim_k('U'); kirim_k('K'); kirim_k('K');  
    kirim_k('A'); kirim_k('N'); kirim_k(' ');  
    kirim_k('S'); kirim_k('U'); kirim_k('H');  
    kirim_k('U'); kirim_k(' '); kirim_k(':');
```

```
}
```

```
void tampilan_suhu_awal()
```

```
{
```

```
  kirim_p(192); kirim_k('2');  kirim_k('6');
```

```
}
```

```
void tampil_suhu()
```

```
{
```

```
  kirim_p(2);          kirim_k('S');  kirim_k('U');  kirim_k('H');
```

```
  kirim_k('U');  kirim_k(':');  kirim_k(' ');
```

```
}
```

```
void tampil_rh()
```

```
{
```

```
  kirim_k('K');  kirim_k('E');  kirim_k('L');
```

```
  kirim_k('E');  kirim_k('M');  kirim_k('B');
```

```
  kirim_k('A');  kirim_k('B');  kirim_k('A');
```

```
  kirim_k('N');  kirim_k(':');  kirim_k(' ');
```

```
}
```

```
void delay_2 ()
```

```
    //prosedure delay_2
```

```
{
```

```
  int x,y=0;
```

```
  ulang8kali:
```

```
  y++;
```

```
  for (x=0; x<30000; x++);
```

```
  if (y<15) goto ulang8kali;
```

```
}
```

```

int cek_keypad(int *cekker)
{
int    suhu_satuan,suhu_puluhan,boleh;
lbh_dr_38:

    kirim_p(2);
    tampil_suhu_input();
    kirim_p(192);
    tampilan_suhu_awal();

//memberi nilai awal register
suhu_satuan=6;
suhu_puluhan=2;
boleh=0;
do
    {
    // tombol up ditekan
    //
    if (tb_up==0)
        {
        delay_2();
        kirim_p(2);
        tampil_suhu_input();
        kirim_p(192);

        suhu_satuan++;
        // cek apakah satuan sdh lebih dari 10
        if (suhu_satuan>=10)
            {
            suhu_puluhan++;
            suhu_satuan=0;

```

```

        }

//tampilkan satuan dan puluhan ke LCD
    kirim_k(suhu_puluhan+48);
    kirim_k(suhu_satuan+48);
}

// tombol down ditekan
//
if (tb_down==0)
    {
    delay_2();
    kirim_p(2);
    tampil_suhu_input();
    kirim_p(192);

    suhu_satuan--;
    // cek apakah satuan sdh kurang lebih dari 0
    if (suhu_satuan<0)
        {
        suhu_puluhan--;
        suhu_satuan=9;
        }

//tampilkan satuan dan puluhan ke LCD
    kirim_k(suhu_puluhan+48);
    kirim_k(suhu_satuan+48);
}

// tombol enter ditekan
if (tb_enter==0)
    {
    *cekker=(suhu_puluhan*10)+suhu_satuan;

```

```

boleh=1;
delay_2();
//jika suhu lebih 39 dan kurang dari 25 lompat ke tampilan awal
if (*cekker >=39) goto lbh_dr_38;
else if (*cekker <=25) goto lbh_dr_38;
//jika kondisi terpenuhi program jalan
else
    {
        clear();          kirim_p(2);
        kirim_k('S');  kirim_k('U');  kirim_k('H');
        kirim_k('U');  kirim_k(' ');  kirim_k(':');
        kirim_k(' ');  kirim_k(suhu_puluhan+48);
        kirim_k(suhu_satuan+48);
    }
}
while (boleh==0);
}

```

```

void cek_kondisi(int *suhu_inputan, float *suhu_data, float *rh_data)
{
int satuan_suhu,puluhan_suhu,satuan_rh,puluhan_rh,koma_suhu,koma_rh;
if (*suhu_data < 32)
    {
        *suhu_data= *suhu_data - 2 ;
    }
if (*suhu_inputan > *suhu_data)
    {
        lampu_ka=0;
        lampu_ki=0;
        kipas_in=1;
    }
}

```

```

        kipas_out=0;
        if (*rh_data<=50)    pemanas=0;
        else pemanas=1;
    }
else if (*suhu_inputan == *suhu_data)
    {
        lampu_ka=1;
        lampu_ki=1;
        kipas_in=1;
        kipas_out=0;
        pemanas=1;
    }
else if (*suhu_inputan < *suhu_data)
    {
        lampu_ka=1;
        lampu_ki=1;
        kipas_in=1;
        kipas_out=1;
        pemanas=1;
    }

clear();
tampil_suhu();
if (*suhu_data>=10)
    {
        puluhan_suhu=*suhu_data/10;
        satuan_suhu=*suhu_data-(puluhan_suhu*10);
        koma_suhu=(*suhu_data-((puluhan_suhu*10)+satuan_suhu))*10;
        kirim_k(puluhan_suhu+48); kirim_k(satuan_suhu+48);
        kirim_k(',');                kirim_k(koma_suhu+48);
    }

```

```

else
    {
        satuan_suhu=*suhu_data;
        koma_suhu=(*suhu_data-satuan_suhu)*10;
        kirim_k(satuan_suhu+48); kirim_k(',');    kirim_k(koma_suhu+48);
    }
kirim_k(' '); kirim_k('0'); kirim_k('C');
kirim_p(192);

tampil_rh();
if ( (*rh_data>=10) || (*rh_data<=99))
    {
        puluhan_rh=*rh_data/10;
        satuan_rh=*rh_data-(puluhan_rh*10);
        kirim_k(puluhan_rh+48);    kirim_k(satuan_rh+48);
    }
else
    {
        satuan_rh=*rh_data;
        kirim_k(satuan_rh+48);
    }

kirim_k('%');
}

void main()
{
value humi_val,temp_val;
unsigned char error,checksum;
unsigned int i;
int suhu_input,red,data_suhu,data_rh;

```



```

start:
P0=0x0FF;
P1=0x0FF;
kipas_in=0;
kipas_out=0;
data_rh=0;
data_suhu=0;
initlcd();
clear();
tampil_suhu_input();
tampilan_suhu_awal();
cek_keypad(&suhu_input);

s_connectionreset();

while (1)
    {
    error=0;
    error+=s_measure((unsigned char*) &humi_val.i,&checksum,HUMI);

    error+=s_measure((unsigned char*) &temp_val.i,&checksum,TEMP);

    if(error!=0) s_connectionreset();

    else
        {
        humi_val.f=(float)humi_val.i;

        temp_val.f=(float)temp_val.i;
        calc_sth11(&humi_val.f,&temp_val.f);

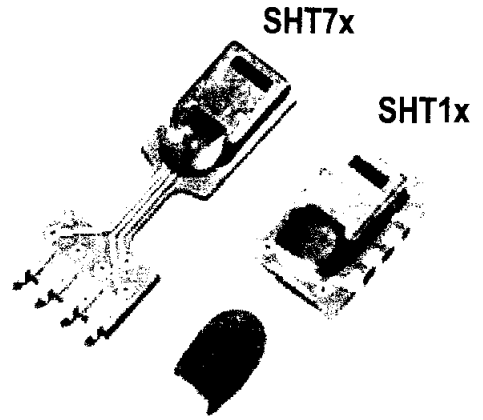
```

```
    }  
clear();  
cek_kondisi(&suhu_input,&temp_val.f,&humi_val.f);  
for (i=0;i<40000;i++)  
{  
if (tb_reset==0) goto start;  
}  
}  
}
```

# SHT1x / SHT7x

## Humidity & Temperature Sensor

**Evaluation Kit Available**



- Relative humidity and temperature sensors
- Dew point
- Fully calibrated, digital output
- Excellent long-term stability
- No external components required
- Ultra low power consumption
- Surface mountable or 4-pin fully interchangeable
- Small size
- Automatic power down

### SHT1x / SHT7x Product Summary

The SHTxx is a single chip relative humidity and temperature multi sensor module comprising a calibrated digital output. Application of industrial CMOS processes with patented micro-machining (CMOSens® technology) ensures highest reliability and excellent long term stability. The device includes a capacitive polymer sensing element for relative humidity and a bandgap temperature sensor. Both are seamlessly coupled to a 14bit analog to digital converter and a serial interface circuit on the same chip. This results in superior signal quality, a fast response time and insensitivity to external disturbances (EMC) at a very competitive price. Each SHTxx is individually calibrated in a precision humidity number. The calibration coefficients are programmed into

the OTP memory. These coefficients are used internally during measurements to calibrate the signals from the sensors.

The 2-wire serial interface and internal voltage regulation allows easy and fast system integration. Its tiny size and low power consumption makes it the ultimate choice for even the most demanding applications.

The device is supplied in either a surface-mountable LCC (Leadless Chip Carrier) or as a pluggable 4-pin single-in-line type package. Customer specific packaging options may be available on request.

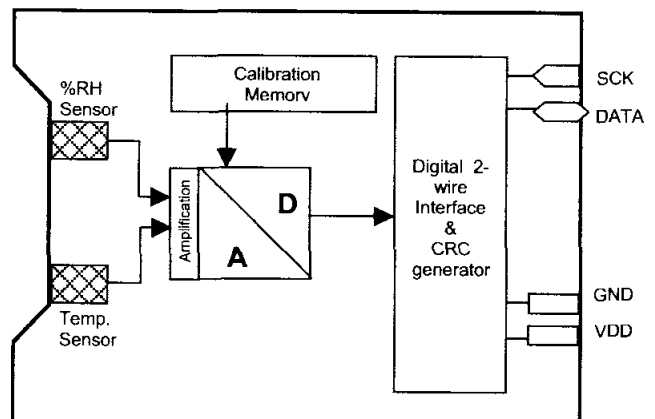
### Applications

- HVAC
- Automotive
- Consumer Goods
- Weather Stations
- Humidifiers
- Dehumidifiers
- Test & Measurement
- Data Logging
- Automation
- White Goods
- Medical

### Ordering Information

Part Number	Humidity accuracy [%RH]	Temperature accuracy [K] @ 25 °C	Package
SHT10	±4.5	±0.5	SMD (LCC)
SHT11	±3.0	±0.4	SMD (LCC)
SHT15	±2.0	±0.3	SMD (LCC)
SHT71	±3.0	±0.4	4-pin single-in-line
SHT75	±1.8	±0.3	4-pin single-in-line

### Block Diagram



## Sensor Performance Specifications

Parameter	Conditions	Min.	Typ.	Max.	Units
<b>Humidity</b>					
Resolution (2)		0.5	0.03	0.03	%RH
		8	12	12	bit
Repeatability			±0.1		%RH
Accuracy (1)	linearized	see figure 1			
Uncertainty					
Interchangeability		Fully interchangeable			
Nonlinearity	raw data		±3		%RH
	linearized		<<1		%RH
Range		0		100	%RH
Response time	1/e (63%) slowly moving air		4		s
Hysteresis			±1		%RH
Long term stability	typical		< 0.5		%RH/yr
<b>Temperature</b>					
Resolution (2)		0.04	0.01	0.01	°C
		0.07	0.02	0.02	°F
		12	14	14	bit
Repeatability			±0.1		°C
			±0.2		°F
Accuracy		see figure 1			
Range		-40		123.8	°C
		-40		254.9	°F
Response Time	1/e (63%)	5		30	s

Table 1 Sensor Performance Specifications

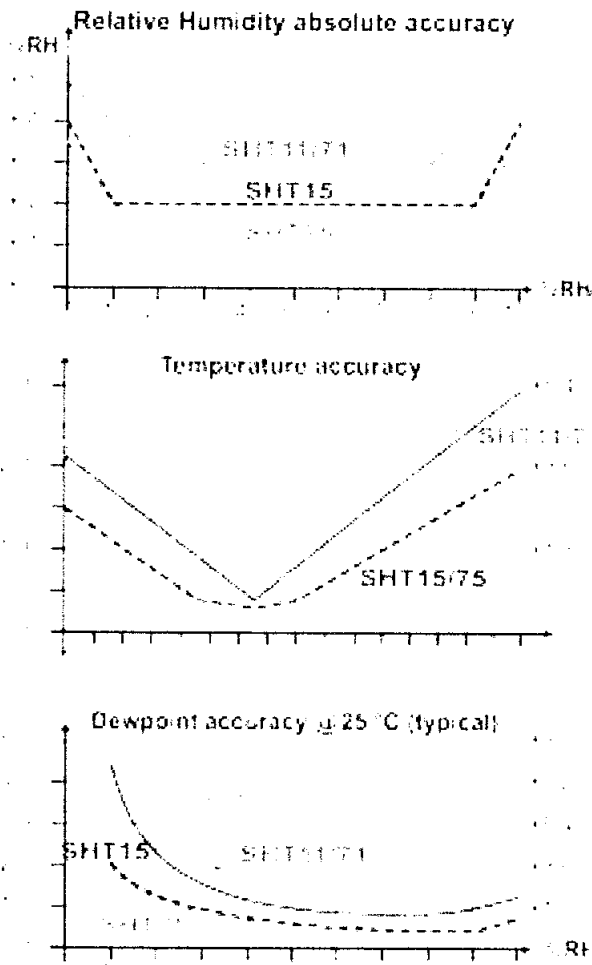


Figure 1 Rel. Humidity, Temperature and Dewpoint accuracies

## Interface Specifications

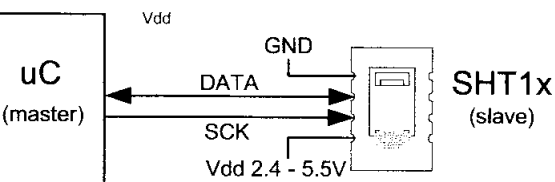


Figure 2 Typical application circuit

### 1 Power Pins

The SHTxx requires a voltage supply between 2.4 and 5.5 V. After powerup the device needs 11ms to reach its "sleep" state. No commands should be sent before that time. Power supply pins (VDD, GND) may be decoupled with a 10 nF capacitor.

### 2 Serial Interface (Bidirectional 2-wire)

The serial interface of the SHTxx is optimized for sensor readout and power consumption and is not compatible with I2C interfaces, see FAQ for details.

#### 2.2.1 Serial clock input (SCK)

The SCK is used to synchronize the communication between a microcontroller and the SHTxx. Since the interface consists of fully static logic there is no minimum SCK frequency.

#### 2.2.2 Serial data (DATA)

The DATA tristate pin is used to transfer data in and out of the device. DATA changes after the falling edge and is valid on the rising edge of the serial clock SCK. During transmission the DATA line must remain stable while SCK is high. To avoid signal contention the microcontroller should only drive DATA low. An external pull-up resistor (e.g. 10 kΩ) is required to pull the signal high. (See Figure 2) Pull-up resistors are often included in I/O circuits of microcontrollers. See Table 5 for detailed IO characteristics.

Each SHTxx is tested to be fully within RH accuracy specifications at 25 °C (77 °F) and 48 °C (118.4 °F)

The default measurement resolution of 14bit (temperature) and 12bit (humidity) can be reduced to 12 and 8 bit through the status register.

**2.3 Sending a command**

To initiate a transmission, a "Transmission Start" sequence has to be issued. It consists of a lowering of the DATA line while SCK is high, followed by a low pulse on SCK and raising DATA again while SCK is still high.



**Figure 3** "Transmission Start" sequence

The subsequent command consists of three address bits (only "000" is currently supported) and five command bits. The SHTxx indicates the proper reception of a command by pulling the DATA pin low (ACK bit) after the falling edge of the 8th SCK clock. The DATA line is released (and goes high) after the falling edge of the 9th SCK clock.

Command	Code
Reserved	0000x
<b>Measure Temperature</b>	<b>00011</b>
<b>Measure Humidity</b>	<b>00101</b>
Read Status Register	00111
Write Status Register	00110
Reserved	0101x-1110x

**Soft reset**, resets the interface, clears the status register to default values  
 wait minimum 11 ms before next command

**Table 2** SHTxx list of commands

**2.4 Measurement sequence (RH and T)**

After issuing a measurement command ('00000101' for RH, '00000111' for Temperature) the controller has to wait for the measurement to complete. This takes approximately 1/55/210 ms for a 8/12/14bit measurement. The exact time varies by up to ±15% with the speed of the internal oscillator. To signal the completion of a measurement, the SHTxx pulls down the data line and enters idle mode. The controller **must** wait for this "data ready" signal before restarting SCK to readout the data. Measurement data is stored until readout,

therefore the controller can continue with other tasks and readout as convenient.

Two bytes of measurement data and one byte of CRC checksum will then be transmitted. The uC must acknowledge each byte by pulling the DATA line low. All values are MSB first, right justified. (e.g. the 5<sup>th</sup> SCK is MSB for a 12bit value, for a 8bit result the first byte is not used).

Communication terminates after the acknowledge bit of the CRC data. If CRC-8 checksum is not used the controller may terminate the communication after the measurement data LSB by keeping ack high.

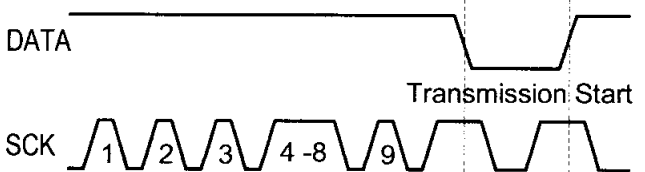
The device automatically returns to sleep mode after the measurement and communication have ended.

**Warning:** To keep self heating below 0.1 °C the SHTxx should not be active for more than 10% of the time (e.g. max. 2 measurements / second for 12bit accuracy).

**2.2.5 Connection reset sequence**

If communication with the device is lost the following signal sequence will reset its serial interface:

While leaving DATA high, toggle SCK 9 or more times. This must be followed by a "Transmission Start" sequence preceding the next command. This sequence resets the interface only. The status register preserves its content.

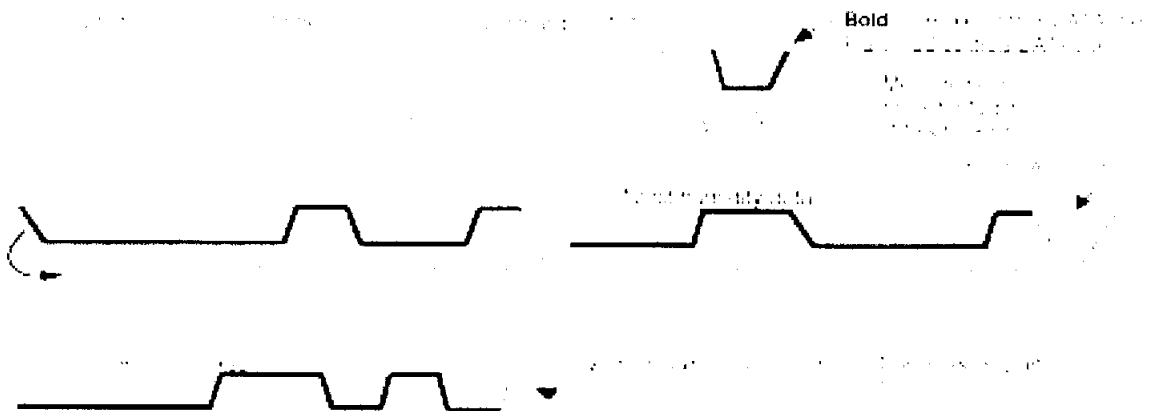


**Figure 4** Connection reset sequence

**2.2.6 CRC-8 Checksum calculation**

The whole digital transmission is secured by a 8 bit checksum. It ensures that any wrong data can be detected and eliminated.

Please consult application note "CRC-8 Checksum Calculation" for information on how to calculate the CRC.



**Figure 5** Example RH measurement sequence for value "0000'1001' 0011'0001"= 2353 = 75.79 %RH (without temperature compensation)

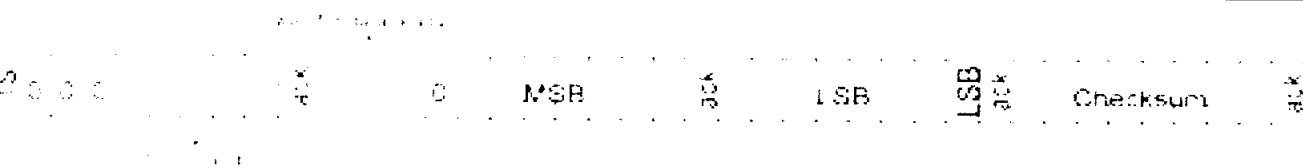


Figure 6 Overview of Measurement Sequence (TS = Transmission Start)

### 3 Status Register

Some of the advanced functions of the SHTxx are available through the status register. The following section gives a brief overview of these features. A more detailed description is available in the application note "Status Register"

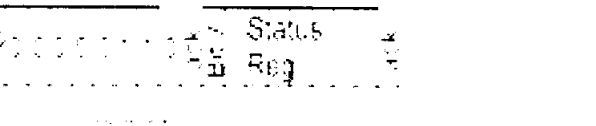


Figure 7 Status Register Write

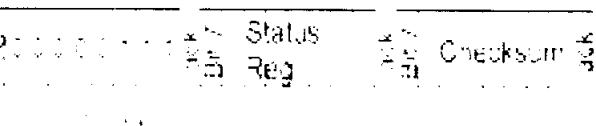


Figure 8 Status Register Read

Type	Description	Default
	reserved	0
R	End of Battery (low voltage detection) '0' for Vdd > 2.47 '1' for Vdd < 2.47	X No default value, bit is only updated after a measurement
	reserved	0
	reserved	0
	For Testing only, do not use	0
R/W	Heater	0 off
R/W	no reload from OTP	0 reload
R/W	'1' = 8bit RH / 12bit Temperature resolution '0' = 12bit RH / 14bit Temperature resolution	0 12bit RH 14bit Temp.

Table 3 Status Register Bits

#### 3.1 Measurement resolution

The default measurement resolution of 14bit (temperature) and 12bit (humidity) can be reduced to 12 and 8bit. This is especially useful in high speed or extreme low power applications.

#### 3.2 End of Battery

The "End of Battery" function detects VDD voltages below 2.47 V. Accuracy is ±0.05 V

#### 3.3 Heater

On chip heating element can be switched on. It will increase the temperature of the sensor by 5-15 °C (9-27 °F). Power consumption will increase by ~8 mA @ 5 V.

Applications:

Comparing temperature and humidity values before and

after switching on the heater, proper functionality of both sensors can be verified.

- In high (>95 %RH) RH environments heating the sensor element will prevent condensation, improve response time and accuracy

**Warning:** While heated the SHTxx will show higher temperatures and a lower relative humidity than with no heating.

### 2.4 Electrical Characteristics<sup>(1)</sup>

VDD=5V, Temperature = 25 °C unless otherwise noted

Parameter	Conditions	Min.	Typ.	Max.	Units
Power supply DC		2.4	5	5.5	V
Supply current	measuring		550		µA
	average	2 <sup>(2)</sup>	28 <sup>(3)</sup>		µA
	sleep		0.3	1	µA
Low level output voltage		0		20%	Vdd
High level output voltage		75%		100%	Vdd
Low level input voltage	Negative going	0		20%	Vdd
High level input voltage	Positive going	80%		100%	Vdd
Input current on pads				1	µA
Output peak current	on			4	mA
	Tristated (off)		10		µA

Table 4 SHTxx DC Characteristics

	Parameter	Conditions	Min	Typ.	Max.	Unit
F <sub>SCK</sub>	SCK frequency	VDD > 4.5 V			10	MHz
		VDD < 4.5 V			1	MHz
T <sub>RFO</sub>	DATA fall time	Output load 5 pF	3.5	10	20	ns
		Output load 100 pF	30	40	200	ns
T <sub>CLx</sub>	SCK hi/low time		100			ns
T <sub>V</sub>	DATA valid time			250		ns
T <sub>SU</sub>	DATA set up time		100			ns
T <sub>HO</sub>	DATA hold time		0	10		ns
T <sub>R</sub> /T <sub>F</sub>	SCK rise/fall time			200		ns

Table 5 SHTxx I/O Signals Characteristics

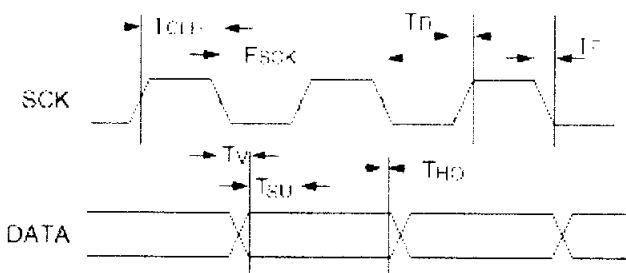


Figure 9 Timing Diagram

Parameters are periodically sampled and not 100% tested  
 With one measurement of 8 bit accuracy without OTP reload per second  
 With one measurement of 12bit accuracy per second

## Converting Output to Physical Values

### 1 Relative Humidity

To compensate for the non-linearity of the humidity sensor and to obtain the full accuracy it is recommended to convert the readout with the following formula<sup>1</sup>:

$$RH_{linear} = c_1 + c_2 \cdot SO_{RH} + c_3 \cdot SO_{RH}^2$$

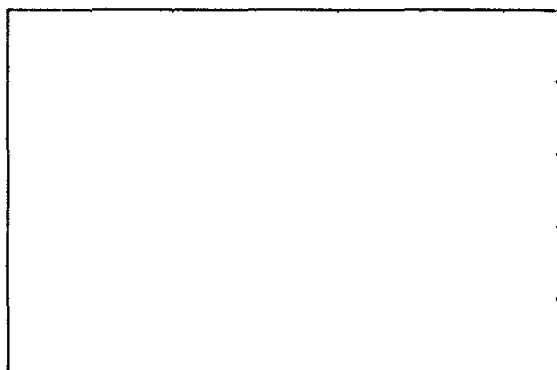
SO <sub>RH</sub>	c <sub>1</sub>	c <sub>2</sub>	c <sub>3</sub>
12 bit	-4	0.0405	-2.8 * 10 <sup>-6</sup>
8 bit	-4	0.648	-7.2 * 10 <sup>-4</sup>

**Table 6** Humidity conversion coefficients

For a simplified, less computation intense conversion formulas see application note "RH and Temperature Non-Linearity Compensation".

Values higher than 99% RH indicate fully saturated air and must be processed and displayed as 100% RH.

The humidity sensor has no significant voltage dependency.



SO<sub>RH</sub> sensor readout (12bit)

**Figure 10** Conversion from SO<sub>RH</sub> to relative humidity

#### 1.1 Humidity Sensor RH/Temperature compensation

For temperatures significantly different from 25 °C (~77 °F) the temperature coefficient of the RH sensor should be considered:

$$RH_{true} = (T_{°C} - 25) \cdot (t_1 + t_2 \cdot SO_{RH}) + RH_{linear}$$

SO <sub>RH</sub>	t <sub>1</sub>	t <sub>2</sub>
12 bit	0.01	0.00008
8 bit	0.01	0.00128

**Table 7** Temperature compensation coefficients

This equals ~0.12 %RH / °C @ 50 %RH

### 3.2 Temperature

The bandgap PTAT (Proportional To Absolute Temperature) temperature sensor is very linear by design. Use the following formula to convert from digital readout to temperature:

$$Temperature = d_1 + d_2 \cdot SO_T$$

VDD	d <sub>1</sub> [°C]	d <sub>1</sub> [°F]	d <sub>2</sub> [°C]	d <sub>2</sub> [°F]
5V	-40.00	-40.00	14bit	0.01
4V	-39.75	-39.50	12bit	0.04
3.5V	-39.66	-39.35		
3V	-39.60	-39.28		
2.5V	-39.55	-39.23		

**Table 8** Temperature conversion coefficients

For improved accuracies in extreme temperatures with more computation intense conversion formulas see application note "RH and Temperature Non-Linearity Compensation".

### 3.3 Dewpoint

Since humidity and temperature are both measured on the same monolithic chip, the SHTxx allows superb dewpoint measurements. See application note "Dewpoint calculation" for more.

## Applications Information

### 1 Operating and Storage Conditions

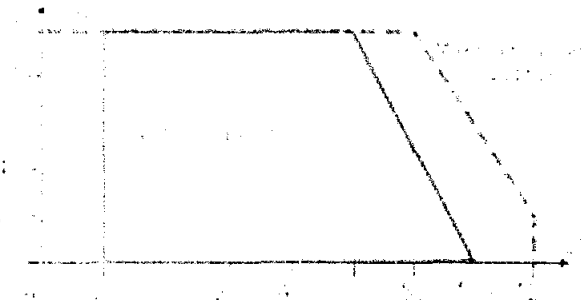


Figure 11 Recommended operating conditions

Conditions outside the recommended range may temporarily offset the RH signal up to  $\pm 3$  %RH. After return to normal conditions it will slowly return towards calibration state by itself. See 4.3 "Reconditioning Procedure" to accelerate this process. Prolonged exposure to extreme conditions may accelerate ageing.

### 2 Exposure to Chemicals

Chemical vapors may interfere with the polymer layers used for capacitive humidity sensors. The diffusion of chemicals into the polymer may cause a shift in both offset and sensitivity. In a clean environment the contaminants will slowly outgas. The reconditioning procedure described below will accelerate this process. High levels of pollutants may cause permanent damage to the sensing polymer.

### 3 Reconditioning Procedure

The following reconditioning procedure will bring the sensor back to calibration state after exposure to extreme conditions or chemical vapors.

0-90 °C (176-194°F) at < 5 %RH for 24h (baking) followed by 0-30 °C (70-90°F) at > 74 %RH for 48h (re-hydration)

### 4 Temperature Effects

The relative humidity of a gas strongly depends on its temperature. It is therefore essential to keep humidity sensors at the same temperature as the air of which the relative humidity is to be measured.

As the SHTxx shares a PCB with electronic components that give off heat it should be mounted far away and below the heat source and the housing must remain well ventilated.

To reduce heat conduction copper layers between the HT1x and the rest of the PCB should be minimized and a slot it may be milled in between (see figure 13).

### 5 Membranes

A membrane may be used to prevent dirt from entering the housing and to protect the sensor. It will also reduce peak concentrations of chemical vapors. For optimal response times air volume behind the membrane must be kept to a minimum. For the SHT1x package Sensirion recommends the SF1 filter cap for optimal IP67 protection.

The temperature sensor passed all tests without any detectable drift. Package and electronics also passed 100%

### 4.6 Light

The SHTxx is not light sensitive. Prolonged direct exposure to sunshine or strong UV radiation may age the housing.

### 4.7 Materials Used for Sealing / Mounting

Many materials absorb humidity and will act as a buffer, increasing response times and hysteresis. Materials in the vicinity of the sensor must therefore be carefully chosen. Recommended materials are: All Metals, LCP, POM (Delrin), PTFE (Teflon), PE, PEEK, PP, PB, PPS, PSU, PVDF, PVF. For sealing and gluing (use sparingly): High filled epoxy for electronic packaging (e.g. glob top, underfill), and Silicone. Outgassing of these materials may also contaminate the SHTxx (cf. 4.2). Store well ventilated after manufacturing or bake at 50°C for 24h to outgas contaminants before packing.

### 4.8 Wiring Considerations and Signal Integrity

Carrying the SCK and DATA signal parallel and in close proximity (e.g. in wires) for more than 10cm may result in cross talk and loss of communication. This may be resolved by routing VDD and/or GND between the two data signals. Please see the application note "ESD, Latchup and EMC" for more information.

Power supply pins (VDD, GND) should be decoupled with a 100 nF capacitor if wires are used.

### 4.9 Qualifications

Extensive tests were performed in various environments. Please contact SENSIRION for detailed information.

Environment	Norm	Results <sup>(1)</sup>
Temperature Cycles	JESD22-A104-B -40 °C / 125 °C, 1000 cy	Within Specifications
HAST Pressure Cooker	JESD22-A110-B 2.3 bar 125 °C 85 %RH	Reversible shift by +2 %RH
High Temperature and Humidity	JESD22-A101-B 85 °C 85 %RH 1250h	Reversible shift by +2 %RH
Salt Atmosphere	DIN-50021ss	Within Spec.
Condensing Air	-	Within Spec.
Freezing cycles fully submerged	-20 / +90 °C, 100 cy 30min dwell time	Reversible shift by +2 %RH
Various Automotive Chemicals	DIN 72300-5	Within Specifications

Table 9 Qualification tests (excerpt)

### 4.10 ESD (Electrostatic Discharge)

ESD immunity is qualified according to MIL STD 883E, method 3015 (Human Body Model at  $\pm 2$  kV)).

Latch-up immunity is provided at a force current of  $\pm 100$  mA with  $T_{amb} = 80$  °C according to JEDEC 17. See application note "ESD, Latchup and EMC" for more information.



## Package Information

### 1 SHT1x (surface mountable)

Pin	Name	Comment
1	GND	Ground
2	DATA	Serial data, bidirectional
3	SCK	Serial clock, input
4	VDD	Supply 2.4 - 5.5 V
5	NC	Remaining pins must be left unconnected

Table 10 SHT1x Pin Description

#### 1.1 Package type

The SHT1x is supplied in a surface-mountable LCC (Leadless Chip Carrier) type package. The sensors housing consists of a Liquid Crystal Polymer (LCP) cap with epoxy solder top on a standard 0.8 mm FR4 substrate. The device is free of Pb, Cd and Hg. (Fully ROHS, WEEE compliant) The device size is 7.42 x 4.88 x 2.5 mm (0.29 x 0.19 x 0.1 inch) and weight 100 mg.

The production date is printed onto the cap in white numbers in the form wwy. e.g. "351" = week 35, 2001.

#### 1.2 Delivery Conditions

The SHT1x are shipped in 12mm tape at 100pcs or 400pcs (SHT10 at 2000pcs only). Reels are individually labelled with barcode and human readable labels. The lot numbers allow full traceability through production, calibration and test.



Figure 12 Tape configuration and unit orientation

#### 1.3 Soldering Information

Standard reflow soldering ovens may be used. For details please see application note "soldering procedure".

For manual soldering contact time must be limited to 5 seconds at up to 350 °C.

After soldering the devices should be stored at >74 %RH for at least 24h to allow the polymer to rehydrate.

Please consult the application note "Soldering procedure" for more information.

#### 5.1.4 Mounting Examples

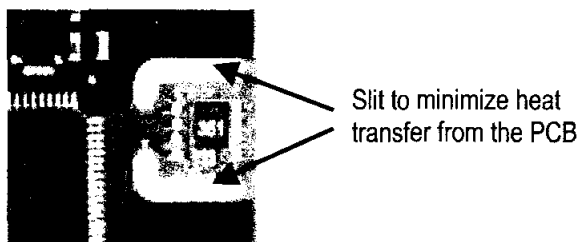


Figure 13 SHT1x PCB Mounting example

The SF1 membrane filter cap is available for optimal IP67 protection. When mounted through a housing the interior can be protected from the environment while still allowing high quality humidity measurements (see example below).

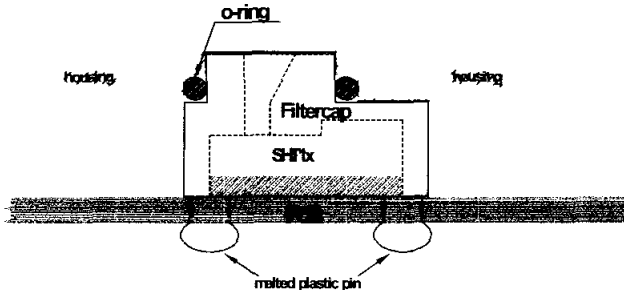


Figure 14 SF1 IP67 filter cap mounting example

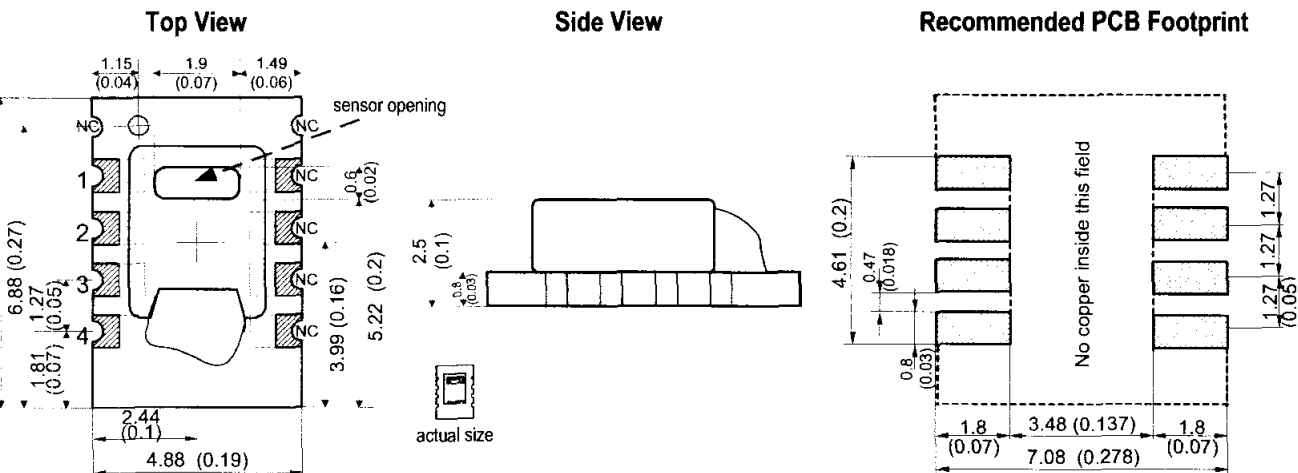


Figure 15 SHT1x drawing and footprint dimensions in mm (inch)

## 2 SHT7x (4-pin single-in-line)

Pin	Name	Comment
1	SCK	Serial clock input
2	VDD	Supply 2.4 - 5.5 V
3	GND	Ground
4	DATA	Serial data bidirectional

**Table 11** SHT7x Pin Description

### 2.1 Package type<sup>1</sup>

The device is supplied in a single-in-line pin type package. The sensor housing consists of a Liquid Crystal Polymer (LCP) cap with epoxy glob top on a standard 0.6 mm FR4 substrate. The device is Cd and Hg free.

The sensor head is connected to the pins by a small bridge to minimize heat conduction and response times. The gold plated back side of the sensor head is connected to the GND pin.

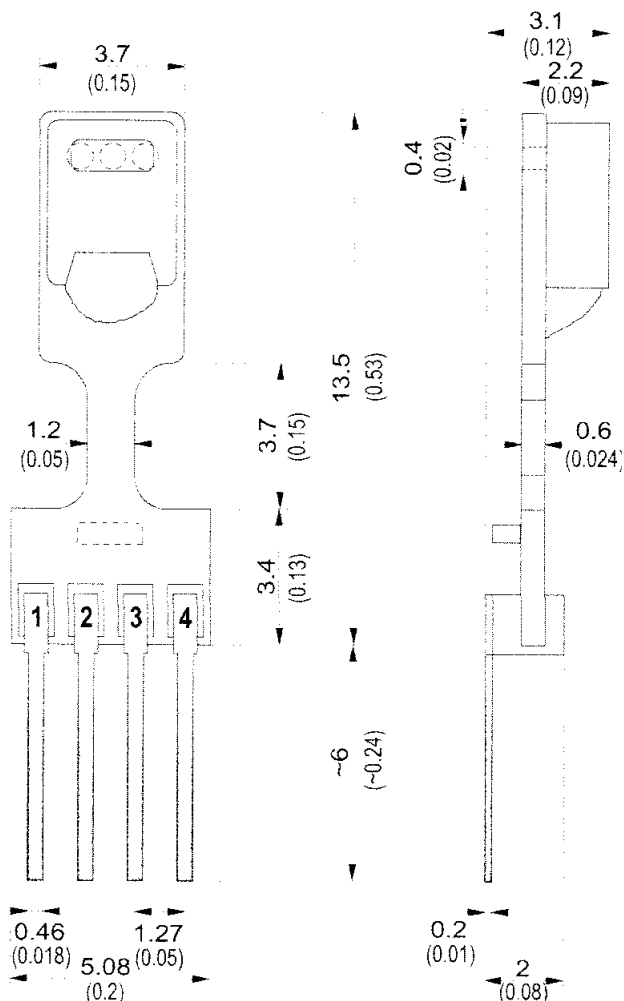
A 100nF capacitor is mounted on the back side between VDD and GND.

All pins are gold plated to avoid corrosion. They can be ordered or mate with most 1.27 mm (0.05") sockets (e.g.: Preci-dip / Mill-Max 851-93-004-20-001 or similar). Total weight: 168 mg, weight of sensor head: 73 mg

The production date is printed onto the cap in white numbers in the form ww.y. e.g. "351" = week 35, 2001.

### 2.2 Delivery Conditions

The SHT7x are shipped in 32 mm tape. These reeled parts in standard option are shipped with 500 units per 13 inch diameter reel. Reels are individually labelled with barcode and human readable labels.



**Figure 17** SHT7x dimensions in mm (inch)



**Figure 16** Tape configuration and unit orientation

### 2.3 Soldering Information<sup>2</sup>

Standard wave SHT7x soldering ovens may be used at maximum 235 °C for 20 seconds.

For manual soldering contact time must be limited to 5 seconds at up to 350 °C.

After wave soldering the devices should be stored at 74 %RH for at least 24 h to allow the polymer to rehydrate.

Please consult the application note "Soldering procedure" for more information.

<sup>1</sup>Other packaging options may be available on request.

<sup>2</sup>For maximum accuracy do not solder SHT75!

## Revision history

Date	Version	Page(s)	Changes
February 2002	Preliminary	1-9	First public release
June 2002	Preliminary		Added SHT7x information
March 2003	Final v2.0	1-9	Major remake, added application information etc. Various small modifications
	V2.01	1-9	Typos, Graph labeling
July 2004	V2.02	1-9	Improved specifications, added SF1 information, improved wording
April 2005	V2.03	1-2	Added SHT10 information
May 2005	V2.04	1-9	Changed company address

The latest version of this document and all application notes can be found at:

## Important Notices

### 7.1 Warning, personal injury

**Do not use this product as safety or emergency stop devices or in any other application where failure of the product could result in personal injury. Failure to comply with these instructions could result in death or serious injury.**

Should buyer purchase or use SENSIRION AG products for any such unintended or unauthorized application, Buyer shall indemnify and hold SENSIRION AG and its officers, employees, subsidiaries, affiliates and distributors harmless against all claims, costs, damages and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death associated with such unintended or unauthorized use, even if such claim alleges that SENSIRION AG was negligent regarding the design or manufacture of the part.

### 7.2 ESD Precautions

The inherent design of this component causes it to be sensitive to electrostatic discharge (ESD). To prevent ESD-induced damage and/or degradation, take normal ESD precautions when handling this product.

See application note "ESD, Latchup and EMC" for more information.

### 7.3 Warranty

SENSIRION AG makes no warranty, representation or guarantee regarding the suitability of its product for any particular purpose, nor does SENSIRION AG assume any liability arising out of the application or use of any product or circuit and specifically disclaims any and all liability, including without limitation consequential or incidental damages. "Typical" parameters can and do vary in different applications. All operating parameters, including "Typical" must be validated for each customer application by customer's technical experts.

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Surabaya ; 01 Agustus 2005

No. 246 /RSAH-Um/III/2005  
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Kepada Yth :

 Ketua Jurusan Teknik Elektro  
Universitas Katolik Widy Mandala

Jl. Kalijudan no. 37


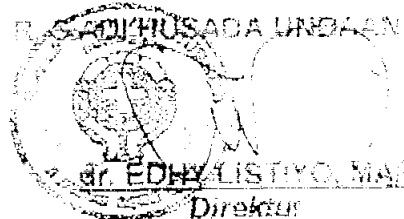
S u r a b a y a

Dengan hormat,

Berkenaan dengan permohonan untuk mencari data rekam medis rekam vital rekam keperawatan oleh mahasiswa teknik elektro UWM an. Hadiyoto Rogong Kusumo (1400069051) untuk keperluan penyusunan skripsi sebagai salah satu data yang diperlukan melalui surat no. 0126/UM06.1/7/2005 tanggal 16 Juli 2005 maka pada prinsipnya kami menyetujui permohonan tersebut

Untuk pelaksanaan lebih lanjut kepada mahasiswa Saudara agar menemui Manajer Perawat di R.S Adi Husada Undangan Wetan pada hari Rabu tanggal 10 Agustus 2005 jam 10.00 WIB di R.S Adi Husada Undangan Wetan Jl. Undangan Wetan 40-44 Surabaya


Demikian kami sampaikan dan anda penerimanya dengan kami ucapkan terima kasih.

R. S. ADI HUSADA UNDANGAN WETAN  
  
  
dr. EDHY LISTIYO, MARS  
Direktur

Tembusan kepada Yth :

- 1. Manajer Perawatan
- 2. Mahasiswa Ybs.
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Surabaya, 12 Agustus 2005

Nomor : 028/VIII/2005  
Perihal : Pemberian ijin tempat pengambilan data

Yth. Ketua Jurusan  
Jurusan Teknik Elektro  
Fakultas Teknik  
Universitas Widya Mandala  
Jalan Kalijudan 37  
S u r a b a y a 60114

Dengan hormat,

Membalas surat tertanggal 19 Juli 2005 Nomor 0128/WM06.1/T/2005 mengenai permohonan ijin tempat mencari data sehubungan dengan pelaksanaan tugas akhir bagi Mahasiswa Fakultas Teknik Jurusan Teknik Elektro Unika Widya Mandala Surabaya.

Dengan ini kami sampaikan bahwa Direksi RSK dapat memberikan ijin kepada:

Nama : Hadisuyoto Poging Yustisia  
NIM : 5103099051  
Judul Proposal : Perancangan dan pembuatan prototype pengaturan suhu pada Inkubator  
Unit Kerja : Sie Teknik

Untuk melaksanakan pengambilan data dan mendapatkan beberapa informasi yang berkaitan dengan inkubator di Rumah Sakit Katolik St. Vincentius a Paulo Surabaya.

Sebelum pengambilan data dimohon mahasiswa berhubungan dengan *Sdr. Bram Dewanto / Kasie Teknik pes.288*.

Terima kasih atas kepercayaan dan perhatiannya pada rumah sakit kami.

Dengan hormat kami,



St. Maria Widjaja SSpS  
Direktur Umum & Adm.Keu.



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wa bersangkutan



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28 Juli 2005

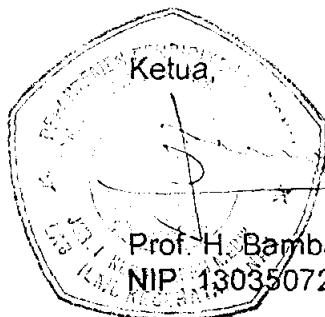
Kepada Yth.  
Kepala Bidang Litbang  
RSU Dr. Soetomo  
Surabaya

Menjawab surat Saudara no : 070/488/304/Litb/VI/2005 tanggal 25 Juli 2005 perihal tersebut pada pokok surat, dengan ini diberitahukan bahwa pada prinsipnya kami tidak keberatan dan dapat memberikan ijin mahasiswa Jurusan Teknik Elektro Fakultas Teknik Univ. Katolik Widyamandala Surabaya a.n. :

Hadisuyoto Poging Yustisia  
NPM : 5103099051

untuk meminjam data guna penyusunan skripsi di Bagian/SMF Ilmu Kesehatan Anak FK Unair/RSU Dr. Soetomo.  
Adapun sebagai pembimbing kami adalah : Risa Etika, dr,SpA.

Demikian untuk diketahui, atas perhatian Saudara kami ucapkan terima kasih.



- Tembusan :
1. Kepala IRNA Anak
  2. Koordinator Penelitian IKA
  3. Risa Etika, dr,SpA
  4. Hadisuyoto Poging Yustisia

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Telepon : (031) 7664811

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2. SMPK Santo Yosef Surabaya Th.1993 - 1996
3. SMUN 4 Surabaya Th.1996 - 1999
4. UNIKA Widya Mandala Surabaya Jurusan Teknik Elektro Th.1999 - 2005